

# Safe and Efficient Reinforcement Learning for Environmental Monitoring

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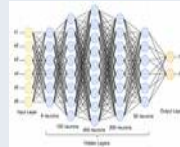
UNIVERSITÀ  
di **VERONA**  
Dipartimento  
di **INFORMATICA**

Ital-IA 2023, 30/05/2023  
Workshop AI per la Sostenibilità

## Research areas



**Reinforcement Learning**



**Machine Learning**



**Planning and High Level Control**



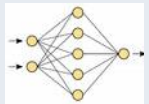
**Time Series Forecasting**



**Logic Programming**



**Anomaly Detection**



**Formal Verification**

## Goals

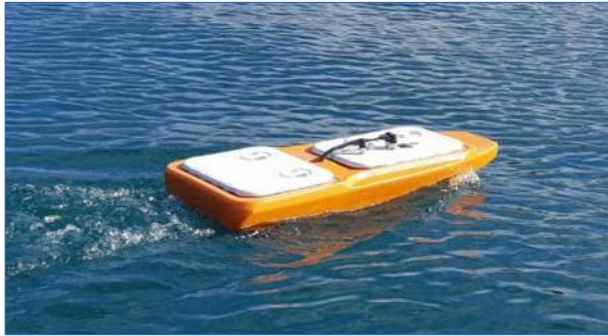


**Efficiency**



**Safety  
Trustability  
Explainability**

## Water Monitoring with ASV

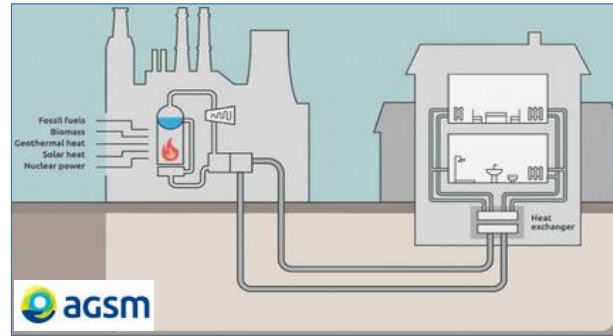


- ≈8.7 M€ funding from EU
- 20 partners across EU
- Tight collaboration with companies



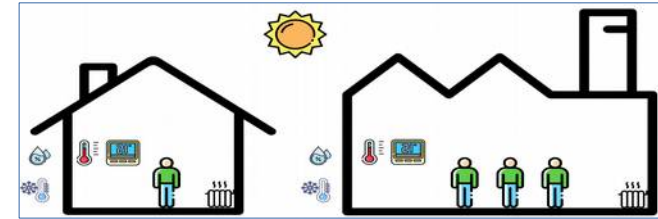
- **Interconnected Nord-Est Innovation (PNRR)**
- ≈110 M€ funding from MUR
- 27 partners across EU
- Tight collaboration with companies

## Efficiency Improvement of District Heating Networks



- **Global HOUse Thermal & Electrical energy Management**
- ≈5.7 M€ funding from EU
- 14 partners across Veneto
- Tight collaboration with companies

## Sustainable Living in Smart Buildings



**SAFE PLACE**



- **Sistemi IoT per ambienti di vita salubri e sicuri**
- ≈8.7 M€ funding from EU
- 20 partners across EU
- Tight collaboration with companies

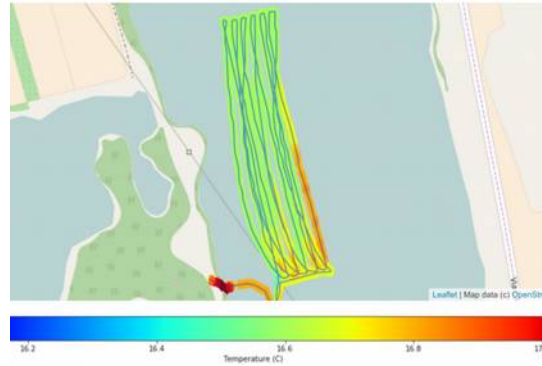


- **Riposizionamento competitivo della filiera del legno**
- ≈4.8 M€ funding from EU
- 17 partners across EU
- Tight collaboration with companies

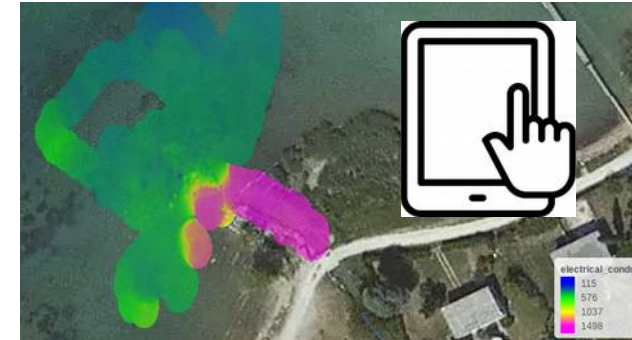
## Operate beyond line of sight



## Repeatable measurements

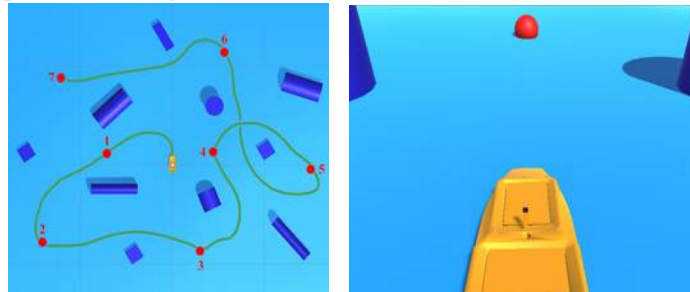


## Citizen science



## Safe DRL for Navigation in Aquatic Scenarios

(shielding based on ANN Verification)



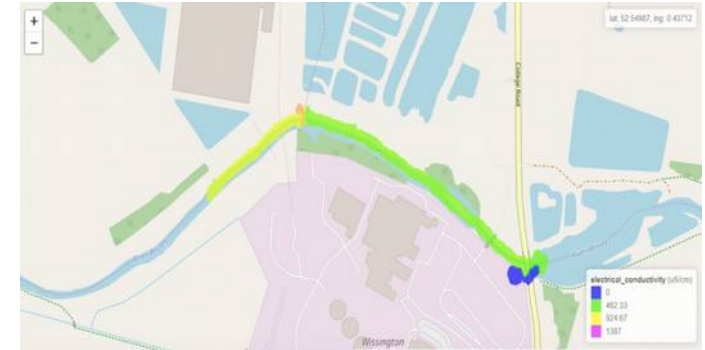
## Planning under Uncertainty for High Level Control




- 10 Drones (3 IT, 3 UK, 2 ESP, 2 GRE)
- **More than 250 data collecting missions** (about 50 UNIVR)
- NGO engagement: 190 individuals (Thames21)
- Engagement of key stakeholders (e.g. ARPAV Italy)
- Data easily available <http://waquin.intcatch.eu/>



**Fimon Lake, IT (DO)**  
Together with ARPAV



**Wissey River, UK (EC)**

- uai** • D. Corsi, E. Marchesini, A. Farinelli, **Formal Verification of Neural Networks for Safety-Critical Tasks in Deep Reinforcement Learning**, in: Proc. 37th Conf. on Uncertainty in Artificial Intelligence (**UAI**), 2021.
- IROS** • E. Marchesini, D. Corsi, A. Farinelli, **Benchmarking safe deep reinforcement learning in aquatic navigation**, in: 2021 IEEE/RSJ International Conference on Intelligent Robots and Systems (**IROS**), 2021.
-  • L. Steccanella, D. D. Bloisi, A. Castellini, A. Farinelli, **Waterline and obstacle detection in images from low-cost autonomous boats for environmental monitoring**, Robotics and Autonomous Systems (**RAS**) 124 (2020) 103346.
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- AAMAS** • G. Mazzi, A. Castellini, A. Farinelli, **Identification of unexpected decisions in partially observable monte-carlo planning: A rule-based approach**, in: Proceedings of the 20th International Conference on Autonomous Agents and MultiAgent Systems (**AAMAS**), IFAAMAS, 2021, p. 889–897.
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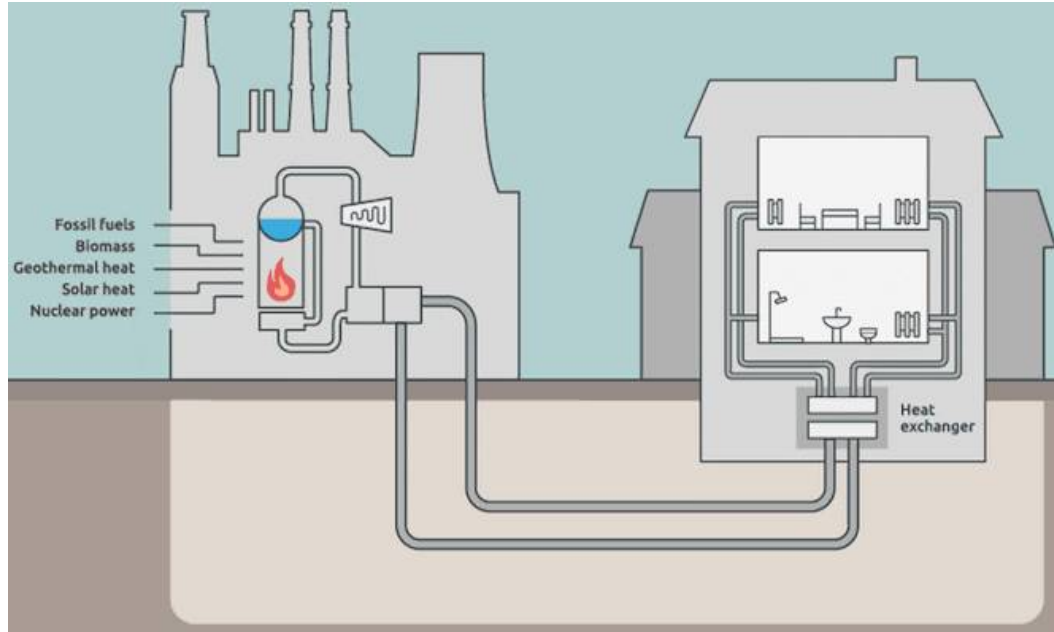
Formal  
Verification  
of RL

Obstacle  
Detection  
(Images)

Obstacle  
Detection  
(Time Series)

Anomaly  
Detection  
and  
Explainability  
(POMDPs)

### District Heating Network



**Goal:** to predict the heating load  
in the next 48 hours

- **Heating and cooling** demand:  
40% of the overall energy usage in Europe
- Pollution control
- Sustainable development
- Improved power station maintenance
- Predictive model **interpretability**

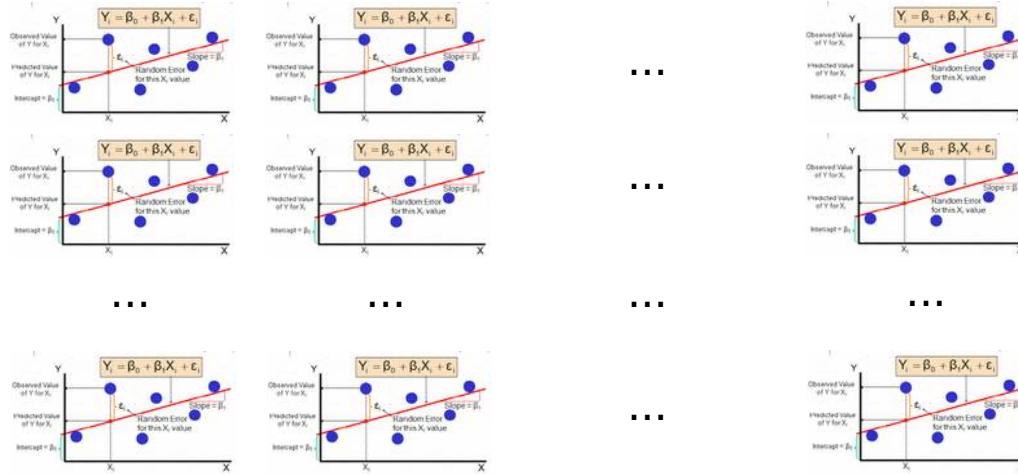
To preserve both **interpretability** and **predictive ability** we used a **multi-equation multivariate linear regression model**

Day of the week

Mon

Tue

Sun



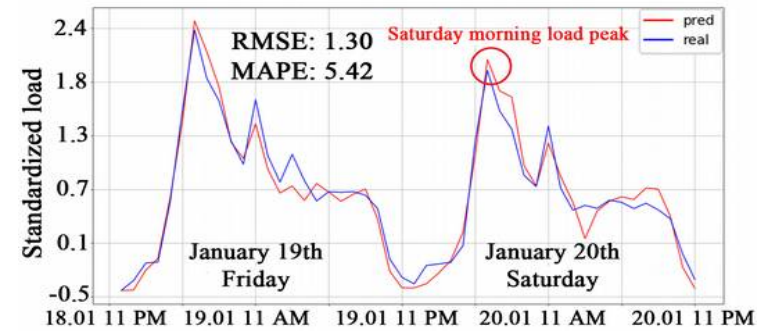
00.00

01.00

23.00






Hour of the day

Results using (interpretable) regression models



Other solutions to forecasting using different methods



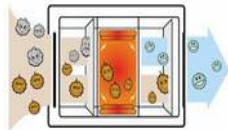
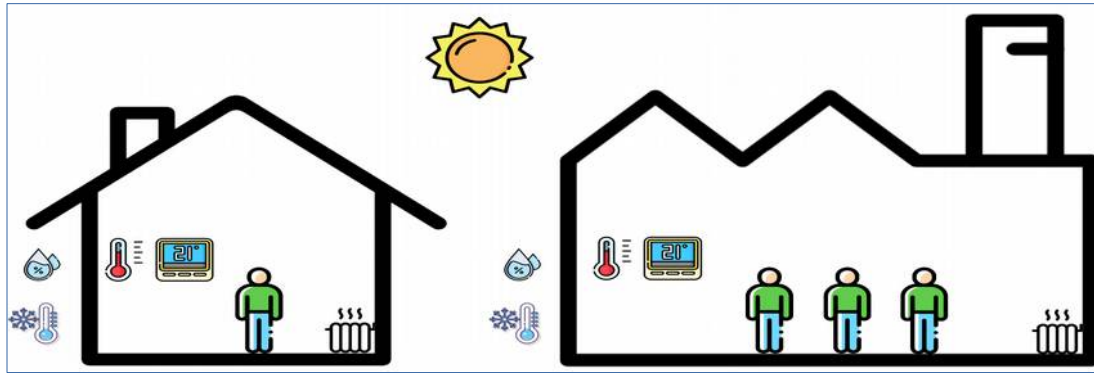
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-  F. Bianchi, A. Castellini, P. Tarocco, A. Farinelli. **Load Forecasting in District Heating Networks: Model Comparison on a Real-World Case Study.** In Proceedings of the Fourth International Conference on Machine Learning, Optimization, and Data Science (LOD), 2019, **LNCS 11943**, pages 553-565, Springer-Verlag, 2020
-  F. Bianchi, P. Tarocco, A. Castellini, A. Farinelli. **Convolutional Neural Network and Stochastic Variational Gaussian Process for Heating Load Forecasting.** In Proceedings of the Fifth International Conference on Machine Learning, Optimization, and Data Science (LOD), 2020, **LNCS 12514**, pages 244-256, Springer-Verlag, 2020
-  F. Bianchi, F. Masillo, A. Castellini, A. Farinelli. **XM HeatForecast: Heating Load Forecasting in Smart District Heating Networks.** In Proceedings of the Fifth International Conference on Machine Learning, Optimization, and Data Science (LOD), 2020, **LNCS 12514**, pages 601-612, Springer-Verlag, 2020

Multivariate  
Regression

CNN and  
GP

Software

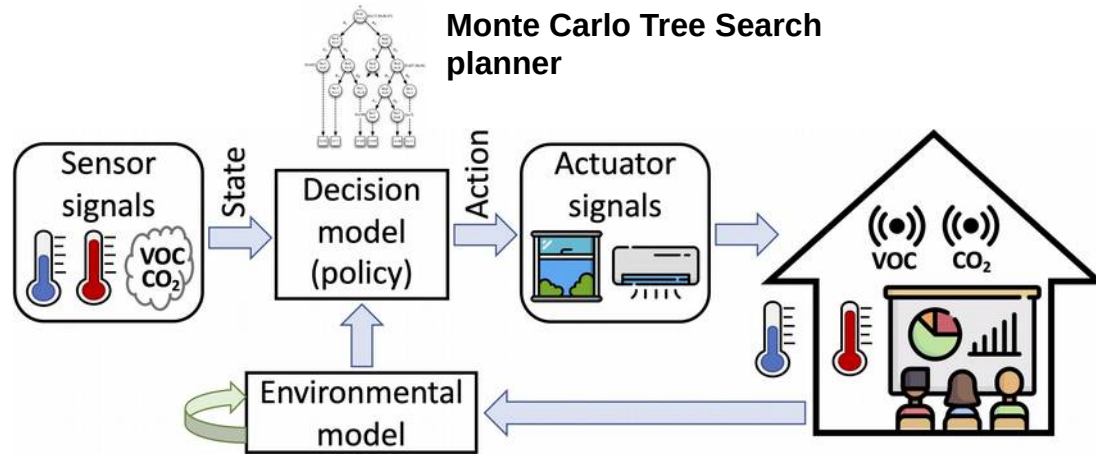
## Smart Buildings



**Goal:** to optimally **control** air quality and thermal comfort in smart buildings

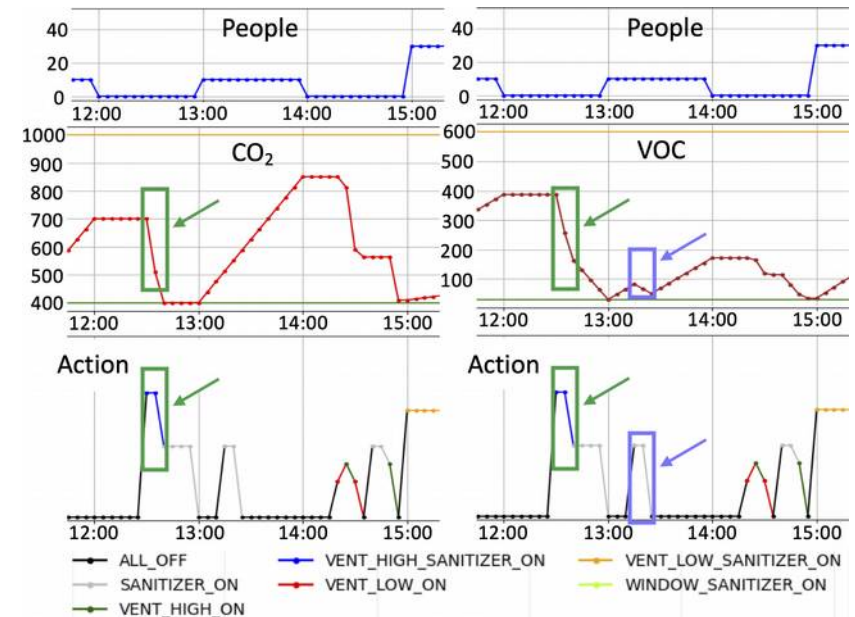
- Measures to counter the SARS-Cov-19 pandemic
- **Sustainable living**
- Improved **indoor air quality**
- Reduced environmental impact of **HVAC** systems
- **Sequential decision making** with **uncertainty**

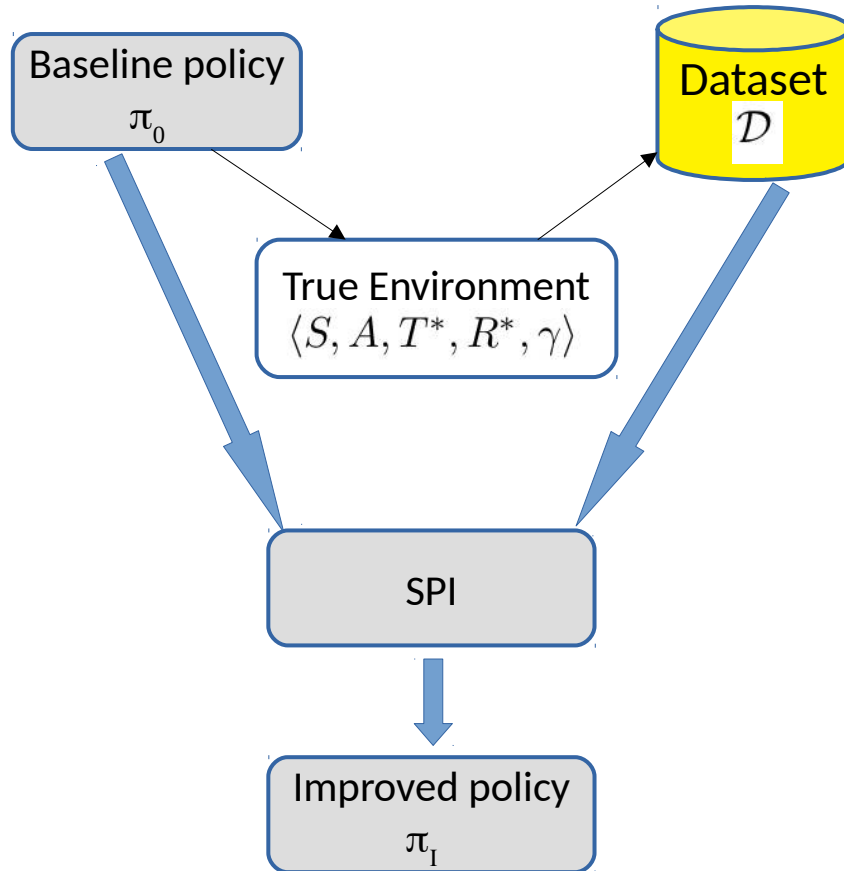
## Framework



## Adaptive RL for Air Quality Control

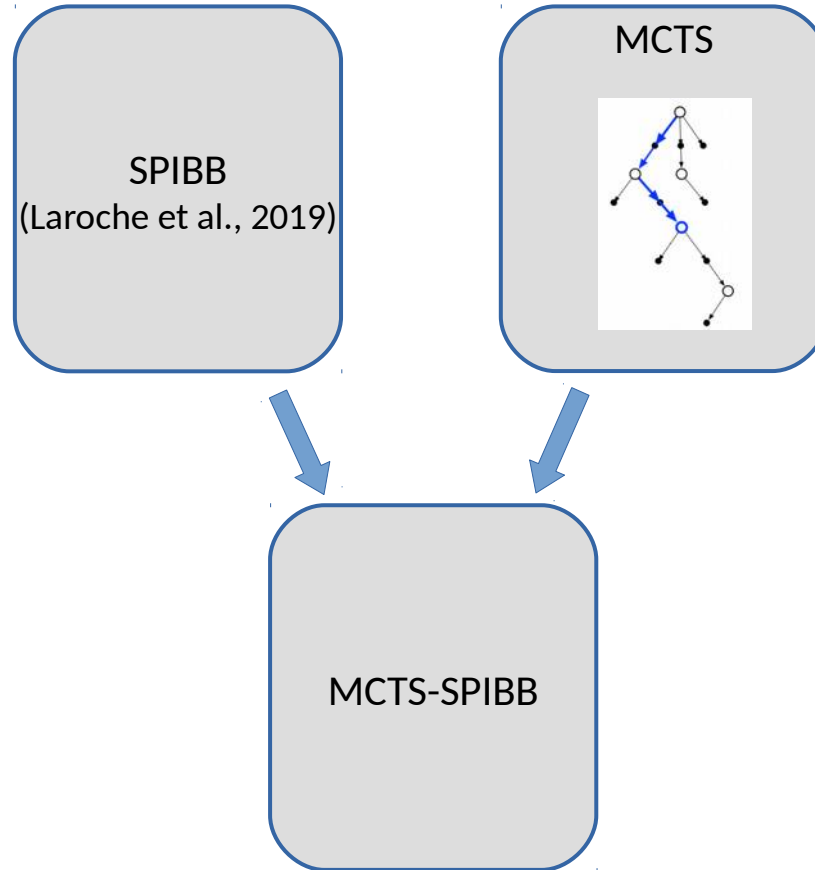
## Results using our MCTS-based planner






## Notation:

- **True environment**  $\langle S, A, T^*, R^*, \gamma \rangle$
  - **Unknown transition model**  $T^*$
  - **Known reward function**  $R^*$
  - **Known baseline policy**  $\pi_0$
  - **Known dataset of trajectories**  
 $\mathcal{D} = \langle s_j, a_j, r_j, s'_j \rangle_{j \in [1, N]}$  generated by the **baseline policy** in the **true environment**
  - **Performance of policy  $\pi$  on environment  $M$ :**  
 $\rho(\pi, M) = V_M^\pi(s_0)$
- Problem: Can we generate a policy  $\pi_1$  that “safely” improves the performance of  $\pi_0$ ?**







- 
 • M. Capuzzo, A. Zanella, M. Zuccotto, F. Cunico, M. Cristani, A. Castellini, A. Farinelli, L. Gamberini, **IoT systems for healthy and safe life environments**, in: 7th IEEE Forum on Research and Technologies for Society and Industry Innovation (**RTSI**), 2022.

Safe Place  
RL/Planning

- 
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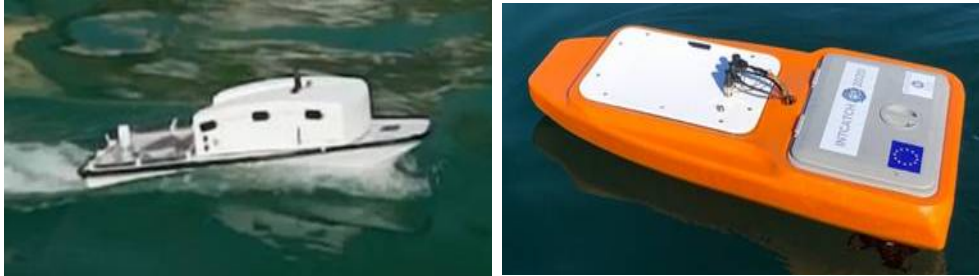
Prior  
Knowledge  
In  
POMCP

- 
 • M. Zuccotto, A. Castellini, A. Farinelli, **Learning state-variable relationships for improving POMCP performance**, in: Proceedings of the 37th ACM/SIGAPP Symposium on Applied Computing (**SAC**), Association for Computing Machinery, 2022, p. 739–747.

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 • A. Castellini, F. Bianchi, E. Zorzi, T. Simao, A. Farinelli, M. Spaan. **Scalable Safe Policy Improvement via Monte Carlo Tree Search**, International Conference on Machine Learning (**ICML**), 2023, accepted.

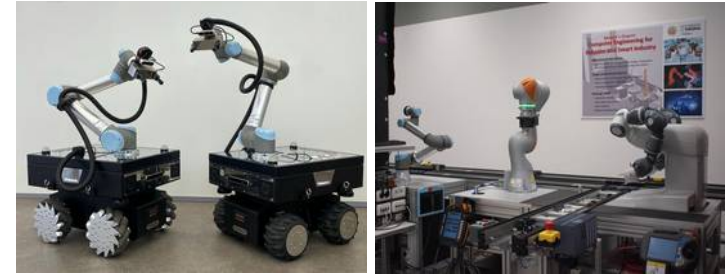
MCTS-SPIBB

## Intcatch drones



3 ASV

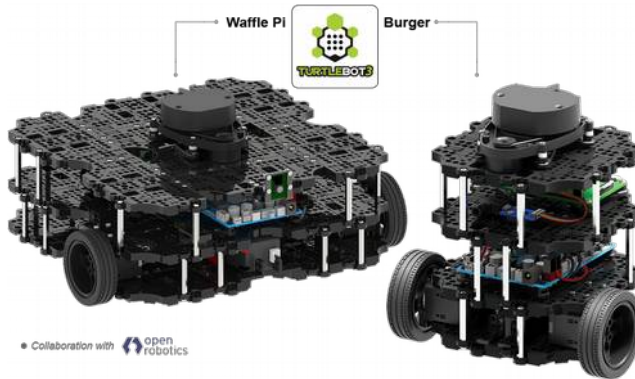
## ICE-Lab: Research infrastructure, realistic production line for validation (<https://www.icelab.di.univr.it/>)



2 RB Kairos

? Kuka?

## Turtlebots



5 Turtlebot3



2 Turtlebot5



**Machine Learning & Deep Learning (12 CFU)**

**Statistical learning (6 CFU)**

**Planning & Automated Reasoning (12 CFU)**

**Knowledge Representation (6 CFU)**

**Reinforcement Learning & Advanced Programming for AI  
(12 CFU)**

**AI in Robotics (6 CFU)**

**Explainable AI (6 CFU)**





F. Trotti  
PhD



A. Farinelli  
PO

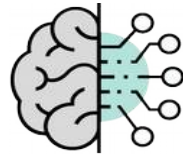
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D. Corsi  
AdR

**Thank you!**



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