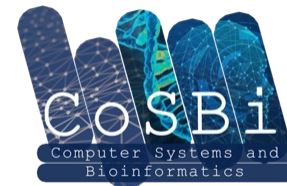
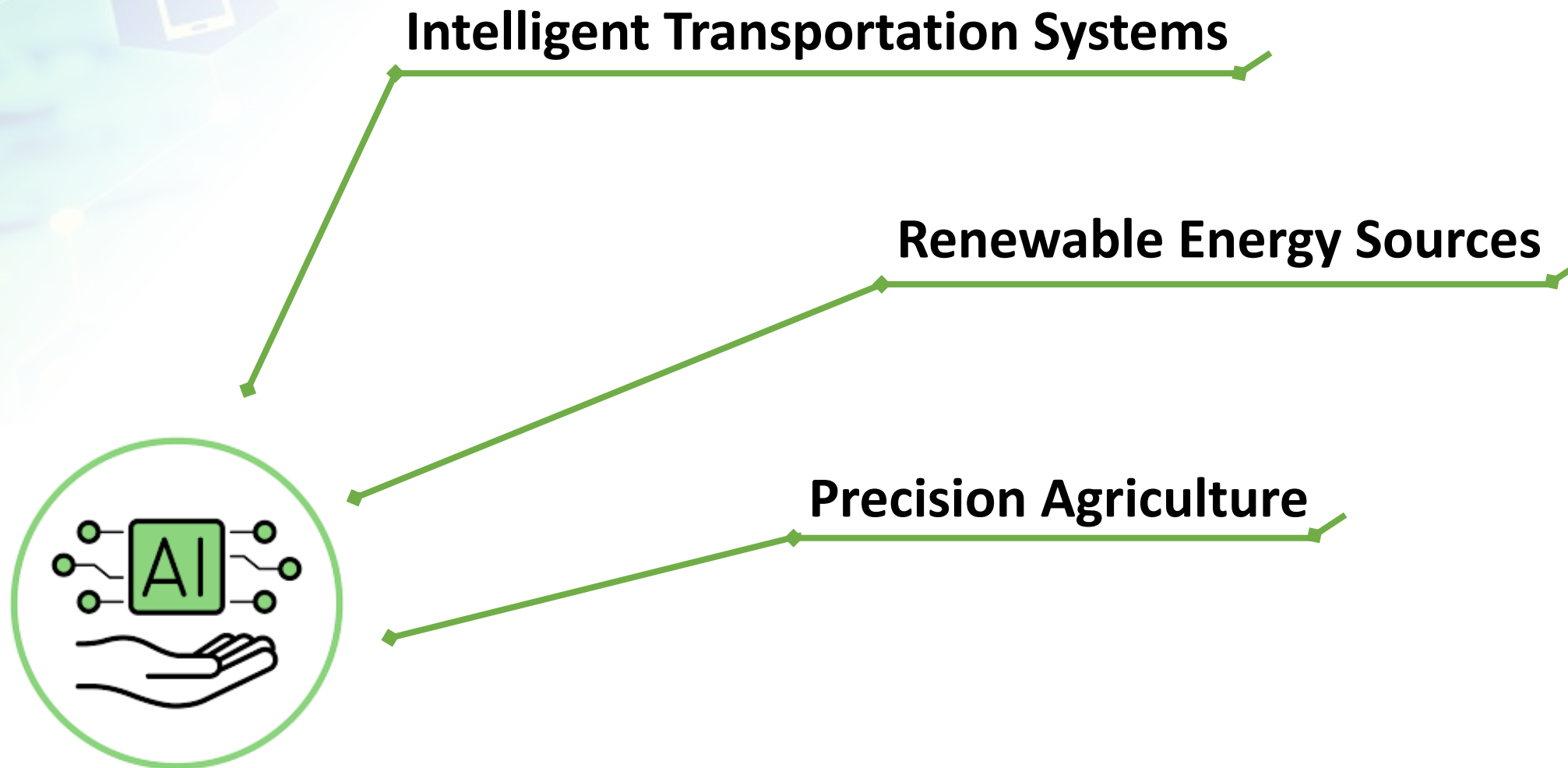


Sustainable AI: inside the deep, alongside the green

Francesco Conte , Ermanno Cordelli , Valerio Guarrasi ,
Giulio Iannello , Rosa Sicilia , Paolo Soda , Matteo Tortora
and Lorenzo Tronchin

Unit of Computer Systems and Bioinformatics,
Universita' Campus Bio-Medico di Roma





Intelligent Transportation Systems

Renewable Energy Sources

Precision Agriculture

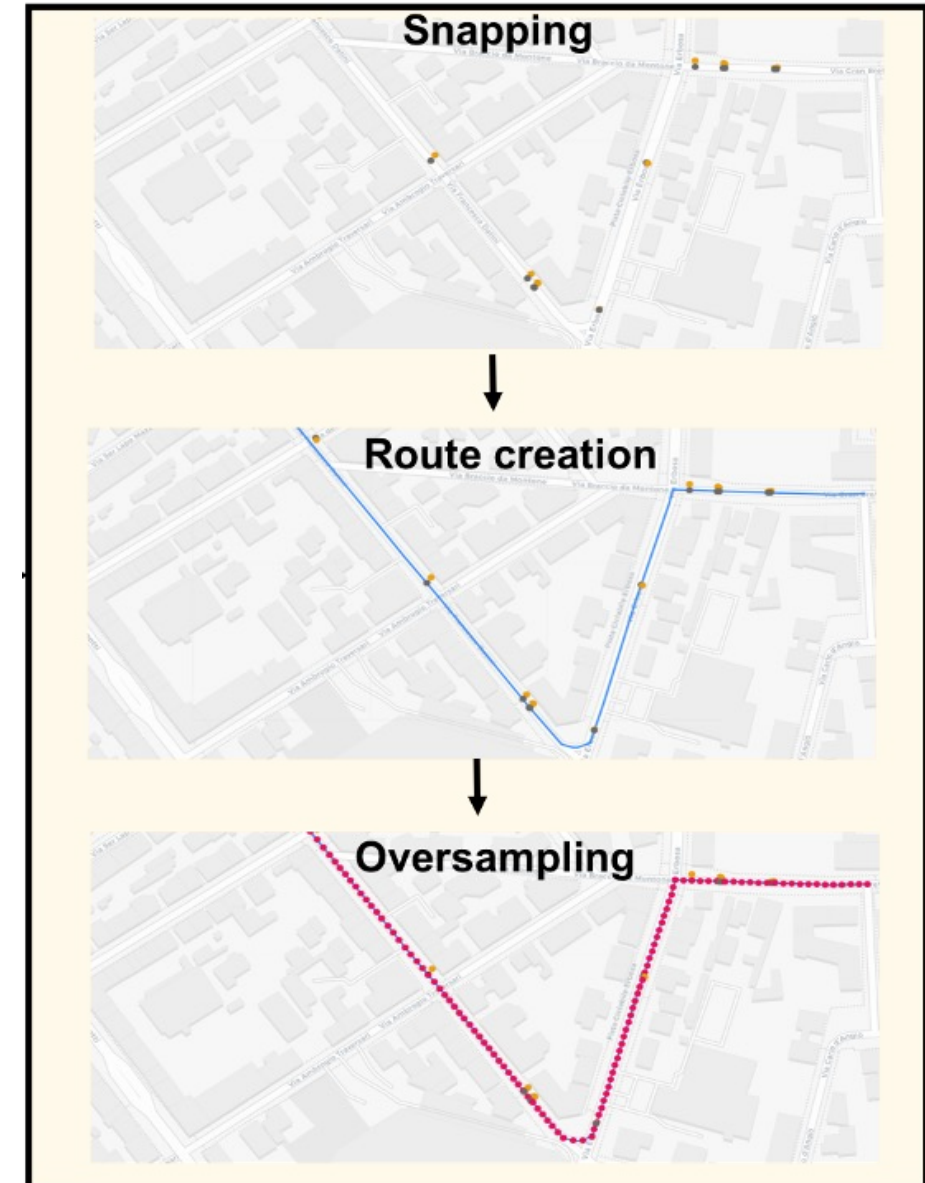
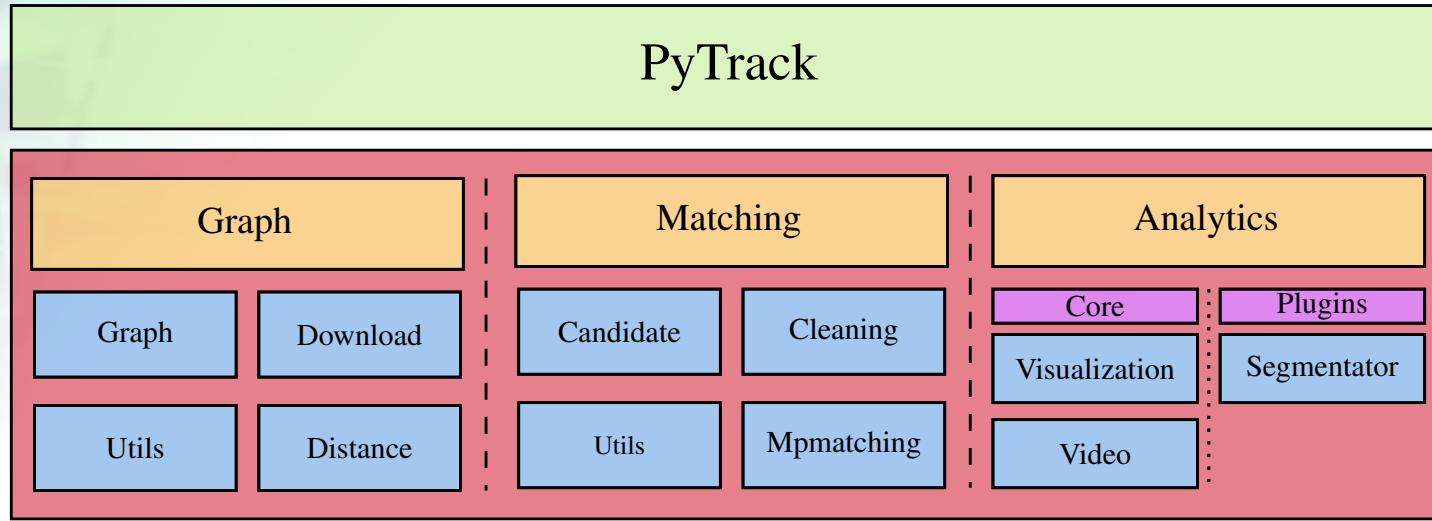


PyTrack: a Map-Matching-based Python Toolbox for Vehicle Trajectory Reconstruction

Map-matching: it is the process to align the GPS sampling data to the actual underlying driving routes network layer.

Main Features:

- Generation of the street network graph using geospatial data from OpenStreetMap
- Map-matching
- Data cleaning
- Video reconstruction of the GPS route
- Visualisation and analysis capabilities



[1] Tortora, Matteo, et al. "PyTrack: A Map-Matching-Based Python Toolbox for Vehicle Trajectory Reconstruction." IEEE Access 10 (2022): 112713-112720.

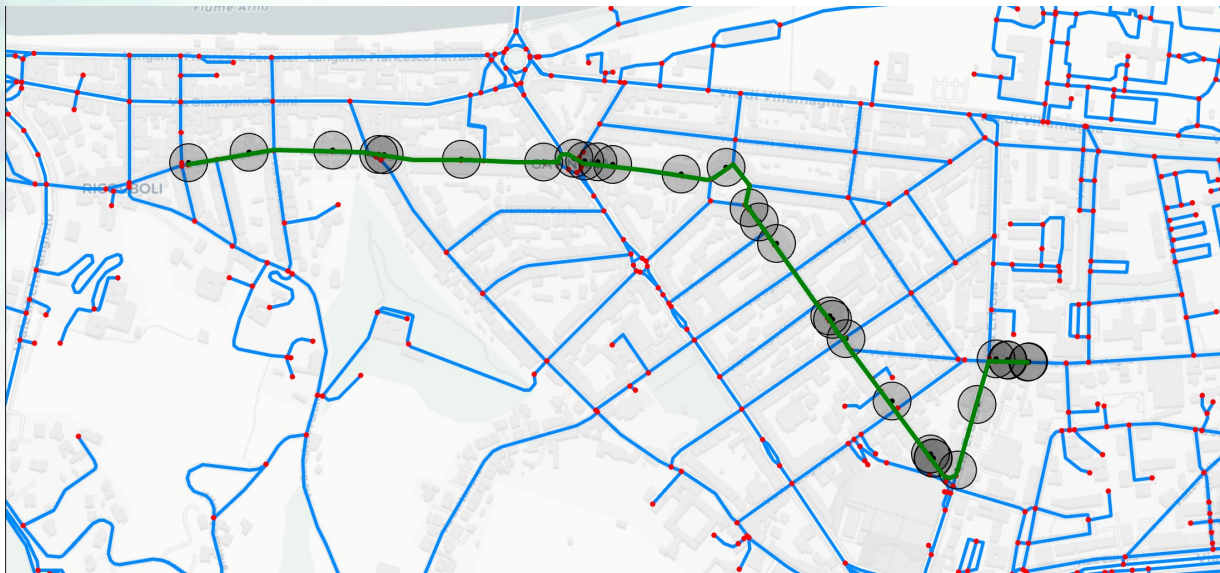
[2] <https://github.com/cosbidev/PyTrack>

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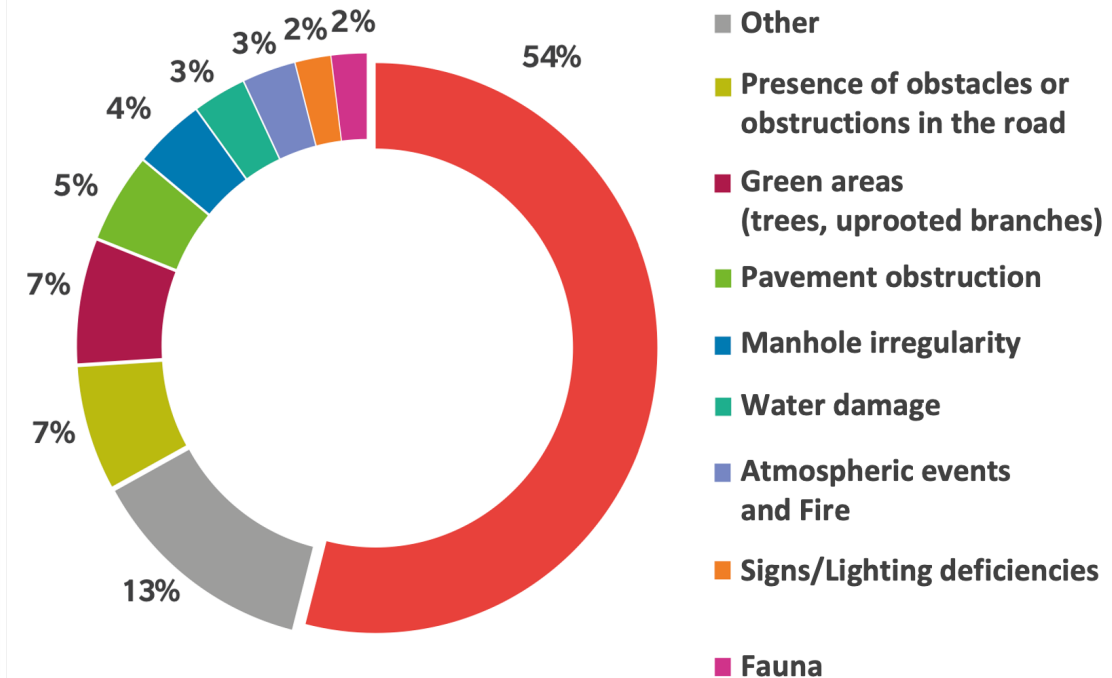


[1] Tortora, Matteo, et al. "PyTrack: A Map-Matching-Based Python Toolbox for Vehicle Trajectory Reconstruction." IEEE Access 10 (2022): 112713-112720.

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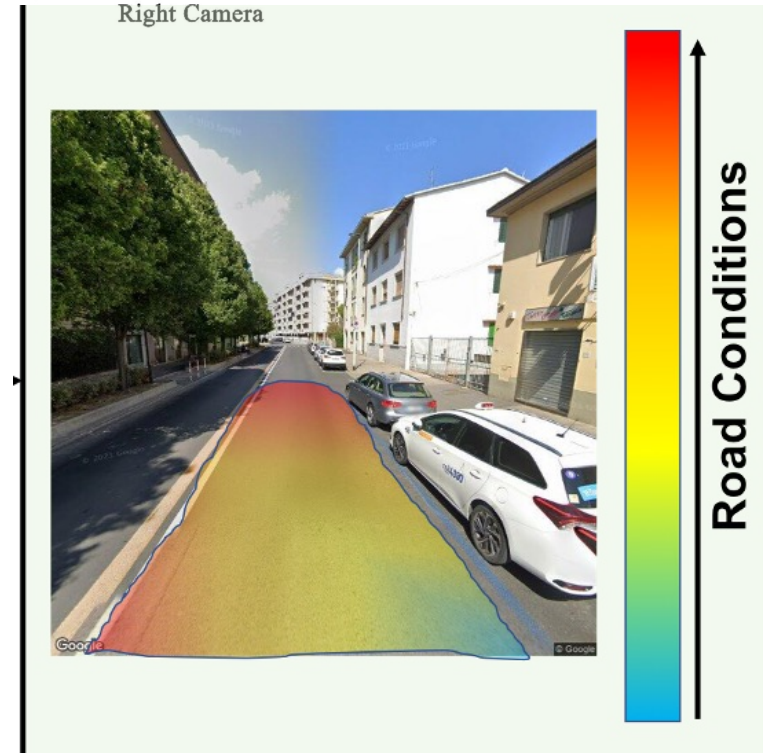
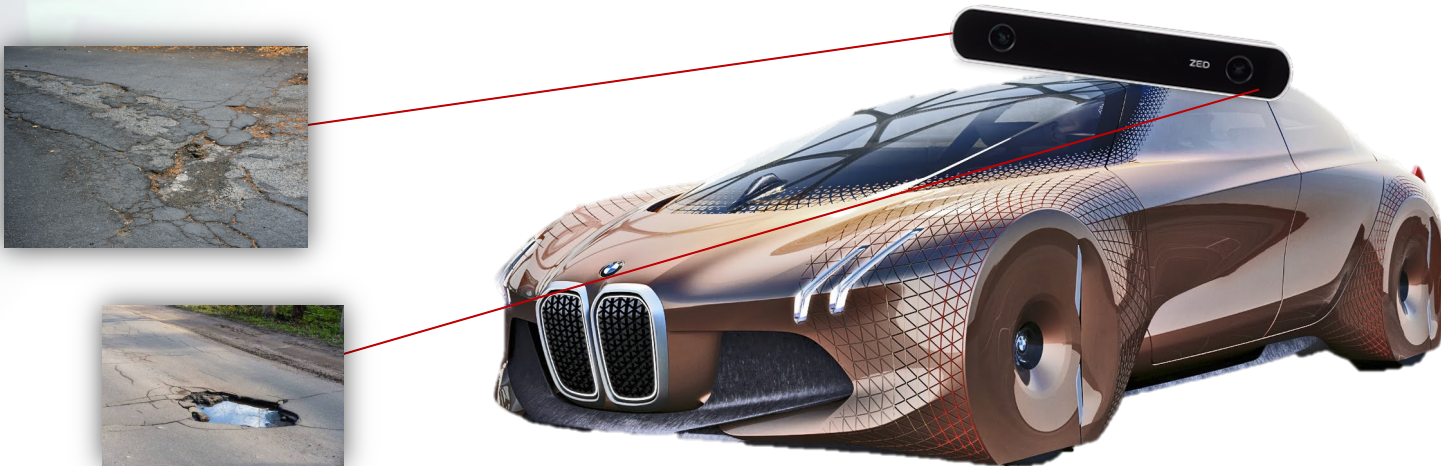
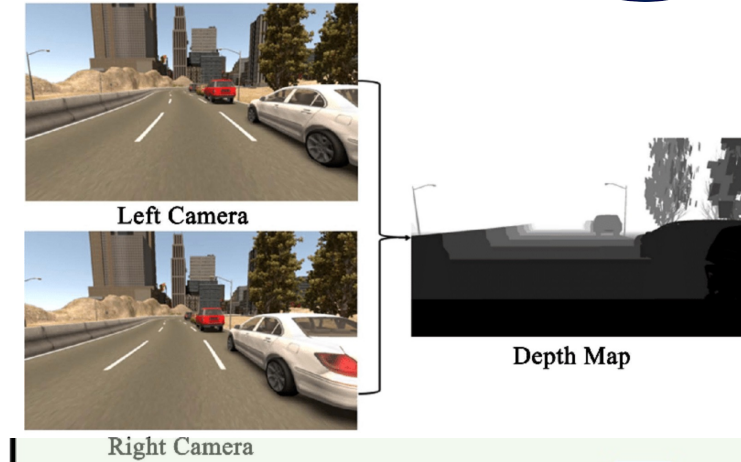
PyTrack: a Map-Matching-based Python Toolbox for Vehicle Trajectory Reconstruction

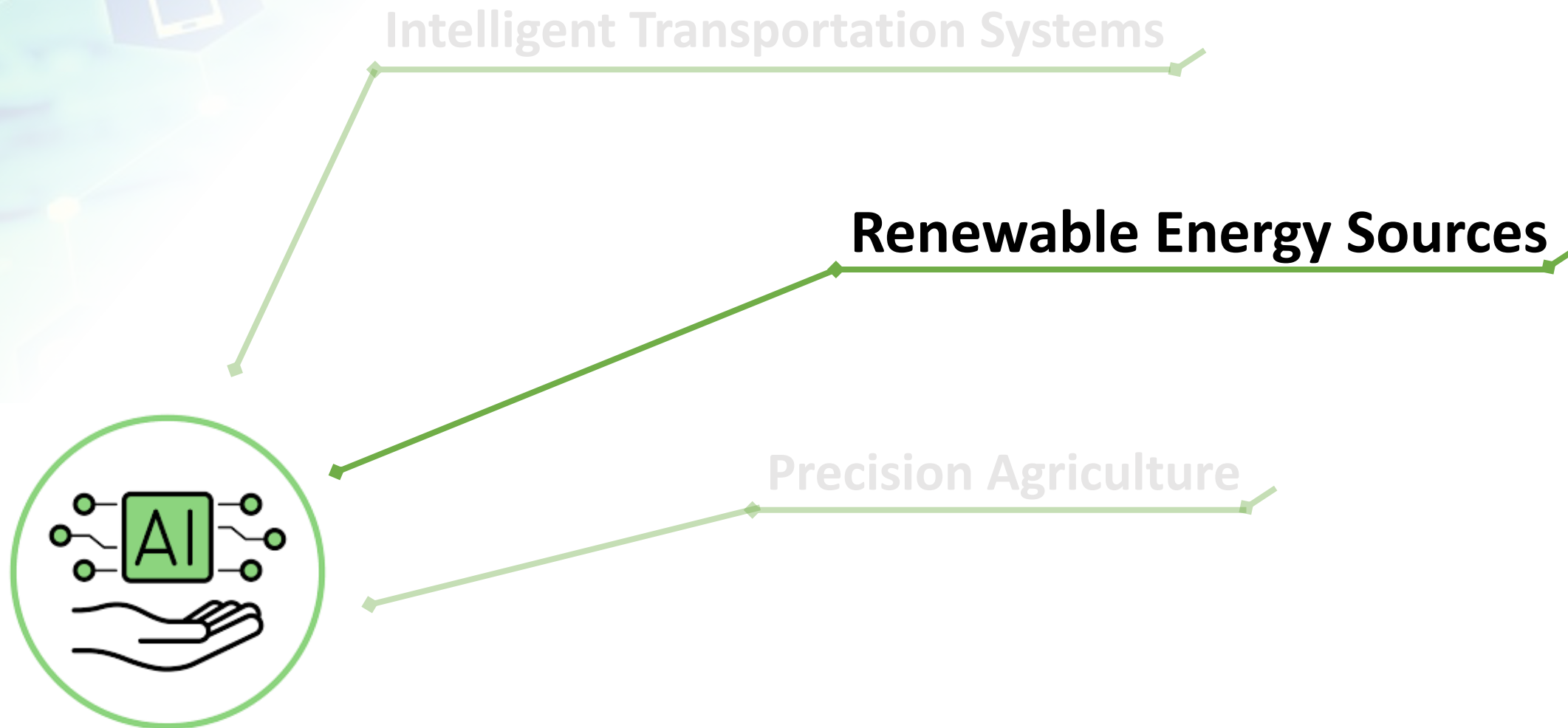
- A significant number of road accidents and vehicle damage occurs as a result of potholes/cracks;
- In most countries, local authorities allocate a significant amount of funds to repair them;
- However, due to their widespread nature, serious injuries or deaths still occur;
- The localisation of potholes/road cracks should thus be an priority to ensure safe driving.



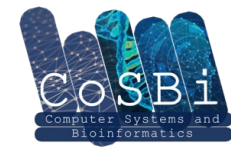
PyTrack: a Map-Matching-based Python Toolbox for Vehicle Trajectory Reconstruction

- The goal of this project is to develop **Computer Vision** methods for the segmentation and localisation of road damage;
- Using a *multimodal* framework approach;
- Use of stereo cameras to acquire depth information; Use of RGB images and depth maps in combination to improve the predictive capability of the method;
- The method aims to improve road safety and vehicle drivability.

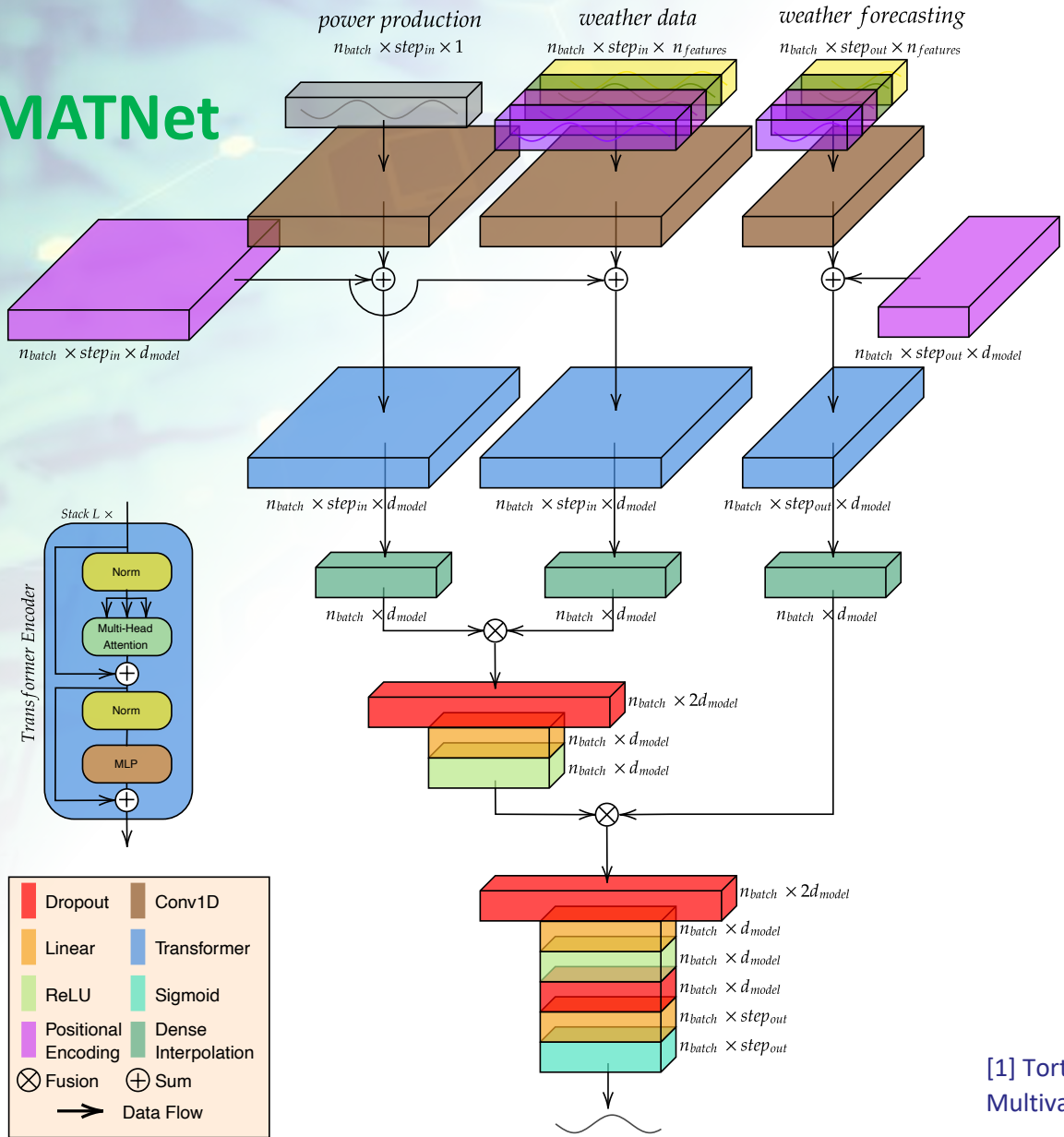




MATNet: a self-attention-based model for PV generation Forecasting



MATNet



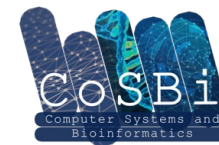
	Dropout		Conv1D
	Linear		Transformer
	ReLU		Sigmoid
	Positional Encoding		Dense Interpolation
\otimes	Fusion	\oplus	Sum
\rightarrow	Data Flow		

Rationale: to provide useful information to facilitate the integration of photovoltaic energy into the modern power grid. [Reference project: **ComER**]

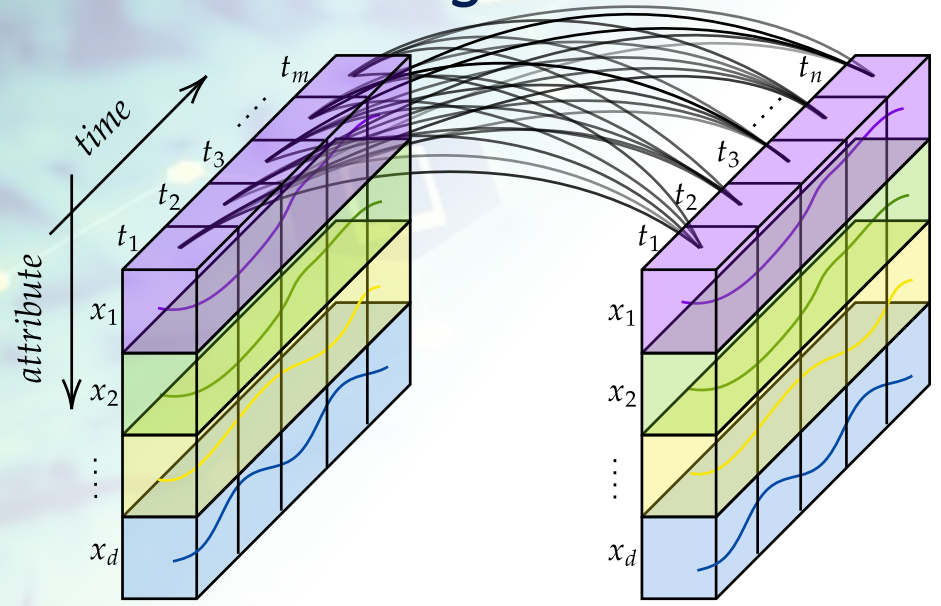
- The attention mechanism is a vital part of the architecture enabling the model to focus on input data elements dynamically
- It is a hybrid approach combining both AI-based and physical-based methods
- We feed the model with historical photovoltaic data and historical and forecast weather data. The first was obtained from the Ausgrid dataset (electricity supplier in southern Australia), and the other two were acquired from OpenWeatherMap.
- We proposed also a dense interpolation module (figure on the left) to simplify the high-dimensional representation returned by the attention-based module.

[1] Tortora, M., et al. »MATNet: Multi-Level Fusion and Self-Attention Transformer-Based Model for Multivariate Multi-Step Day-Ahead PV Generation Forecasting«, submitted to Energy and AI (2023).

MATNet: a self-attention-based model for PV generation

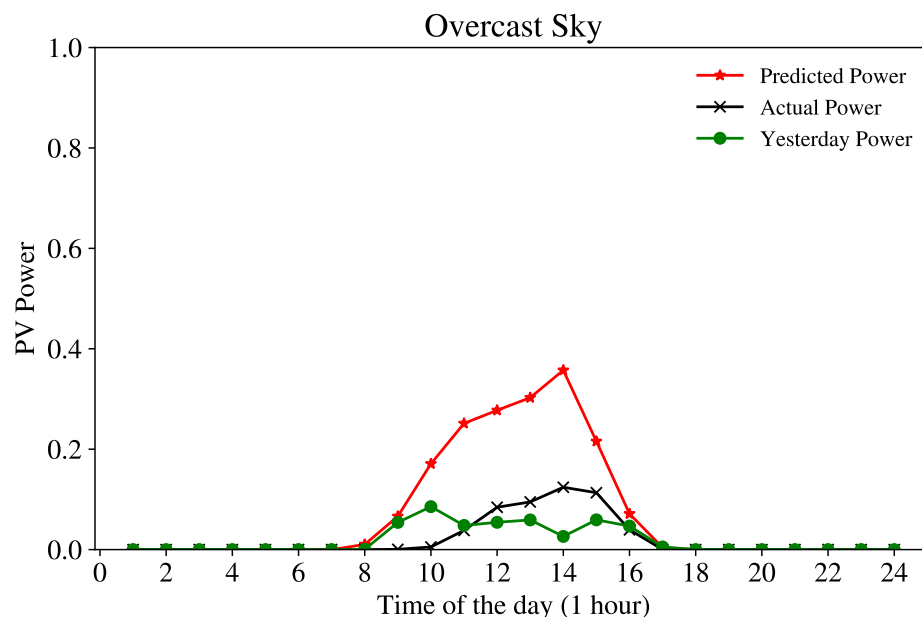
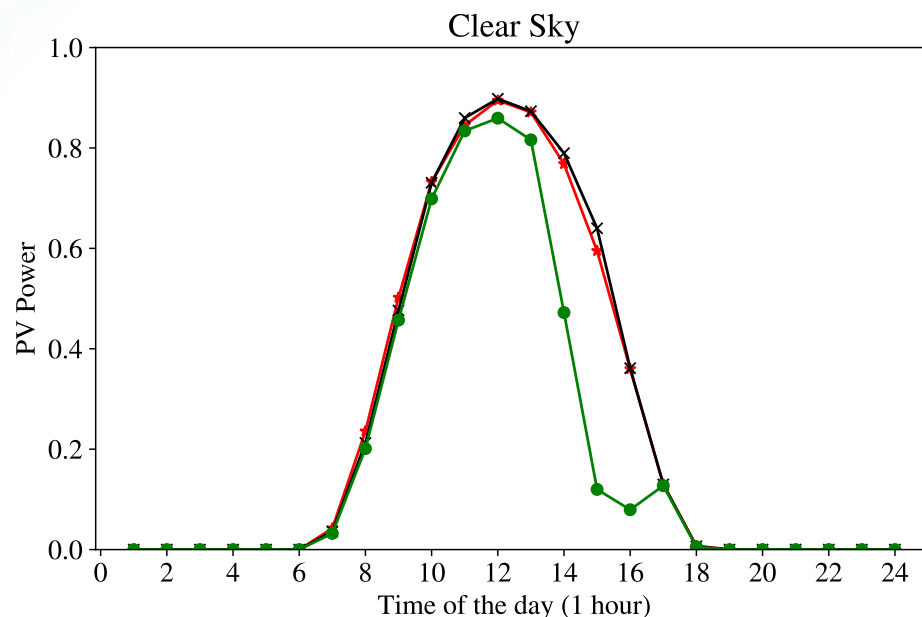


Forecasting W

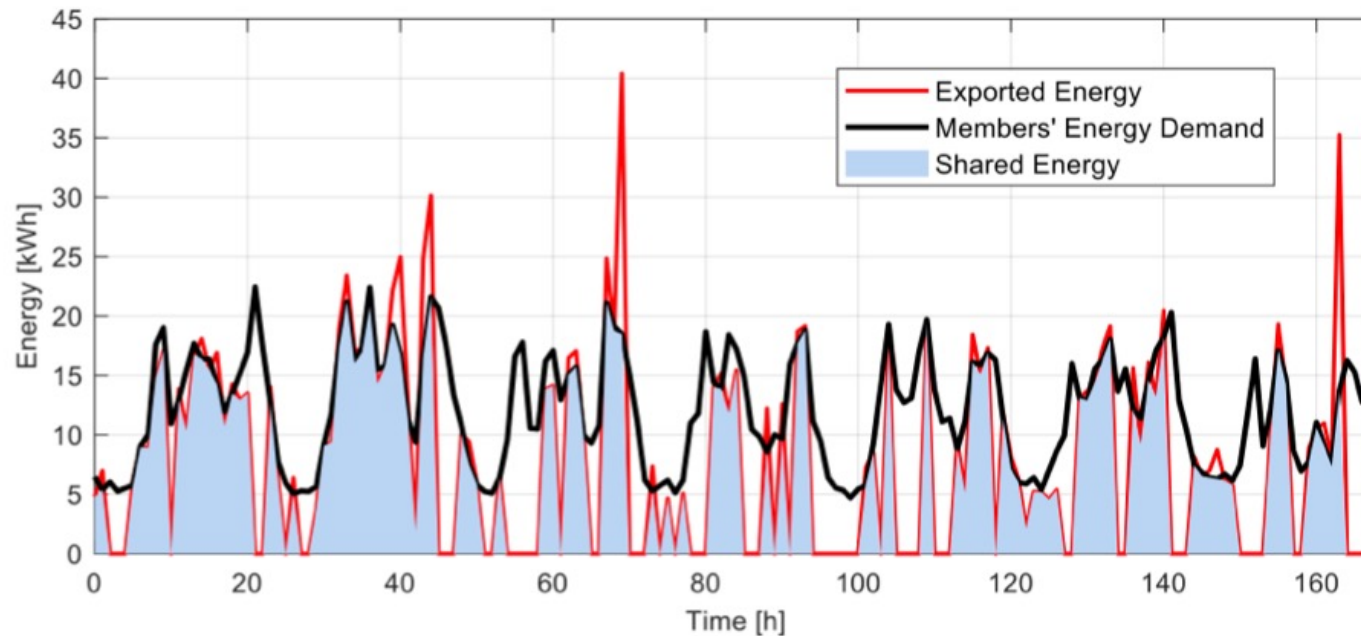
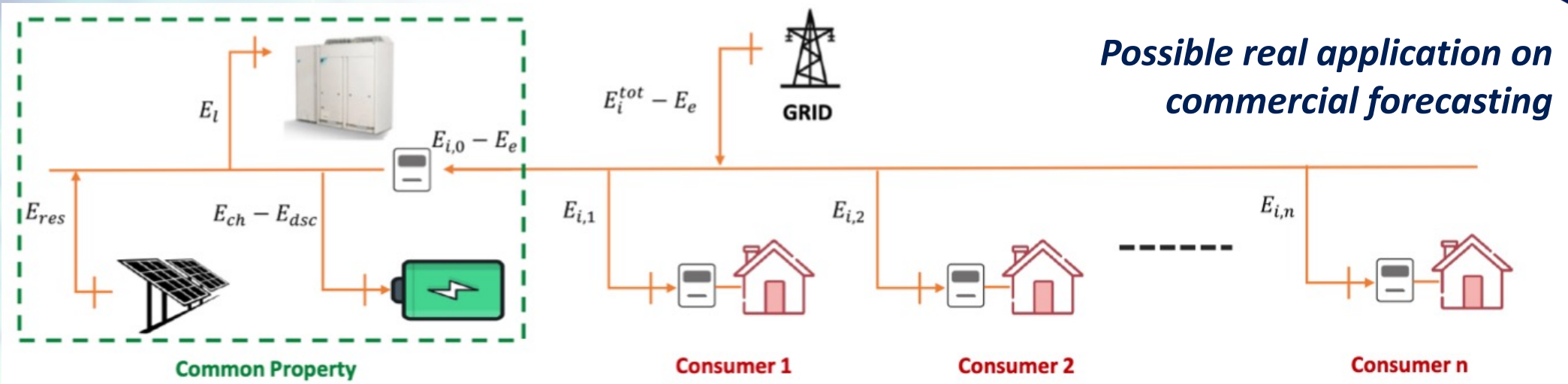


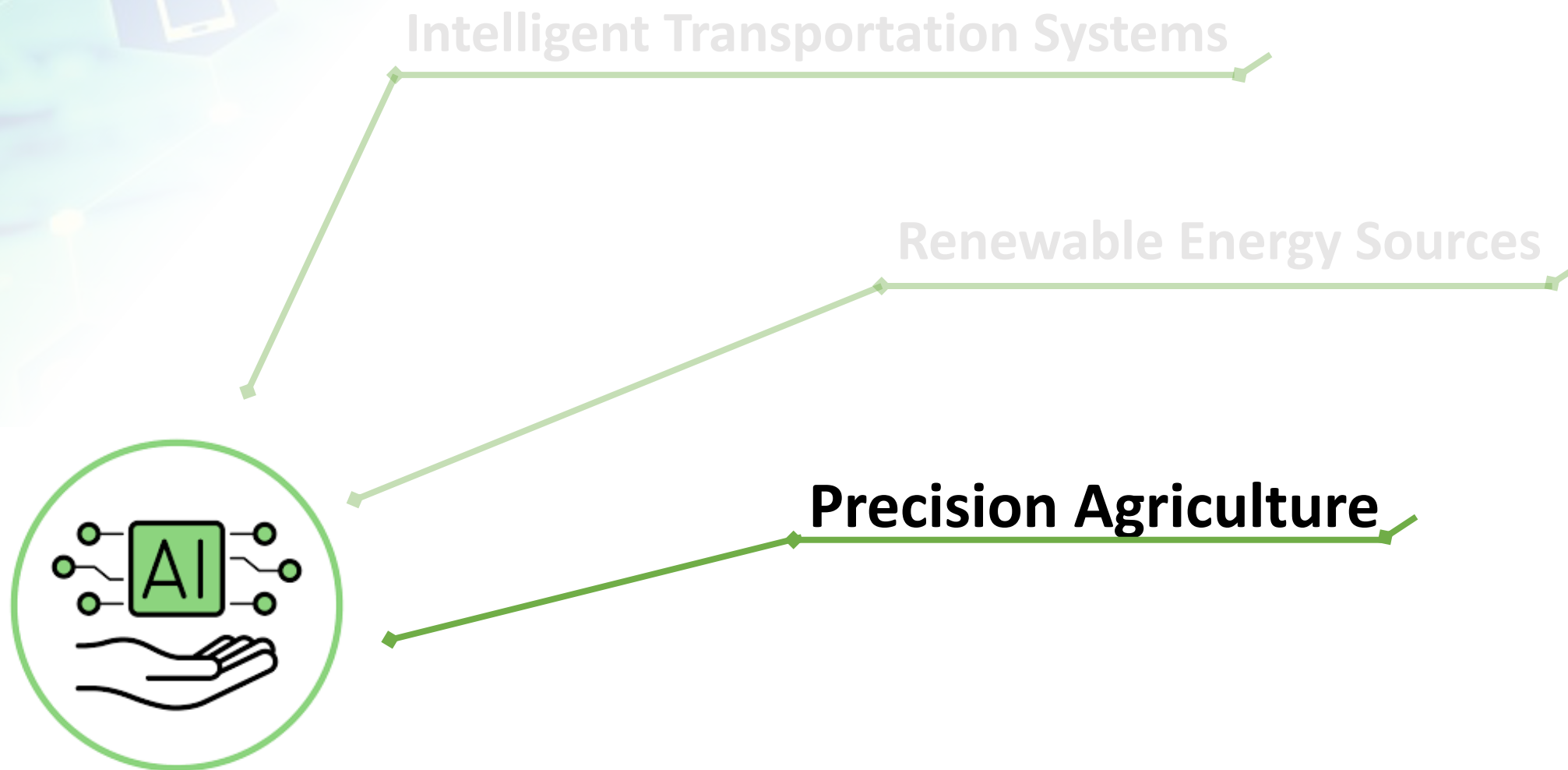
Rationale: to provide useful information to facilitate the integration of photovoltaic energy into the modern power grid.
 [Reference project: **ComER**]

Architecture	MSE	RMSE	MAE	WMAPE	MASE
LsSVR [11]	-	-	4.95*	-	-
Bayesian BiLSTM [12]	-	0.0985	0.0679	-	-
Improved-Bayesian BiLSTM [13]	-	0.0854	0.0370	-	-
LSTM-based MATNet	0.0077	0.0723	0.0390	0.3007	0.7039
GRU-based MATNet	0.0070	0.0720	0.0392	0.2909	0.6934
BiLSTM-based MATNet	0.0085	0.0793	0.0432	0.3159	0.7494
BiGRU-based MATNet	0.0072	0.0724	0.0391	0.2824	0.6729
MATNet_wDIL[22][†]	0.0851	0.2899	0.1589	1.206	2.9242
MATNet	0.0062	0.0673	0.0366	0.2608	0.6265



MATNet: a self-attention-based model for PV generation Forecasting

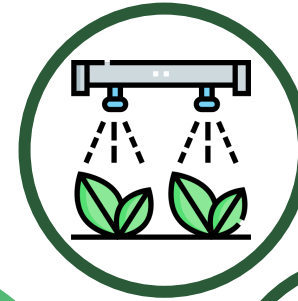




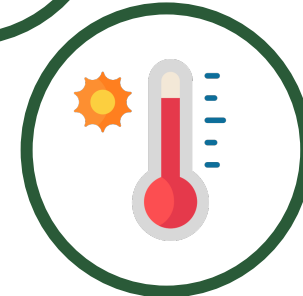
Low Orchard Productivity Assessment exploiting Artificial Intelligence (AI)

- Mapping of the Kiwifruit Vine Decline Syndrome (KVDS), known as **Moria**, phenomenon on G3
- Using *satellite* image data

KVDS is a **complex phenomenon** generated by several factors **working in synergy** with each other.



Irrigation



Temperature



Fertilization

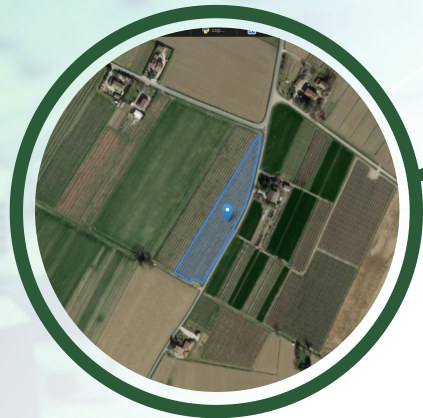


Weather

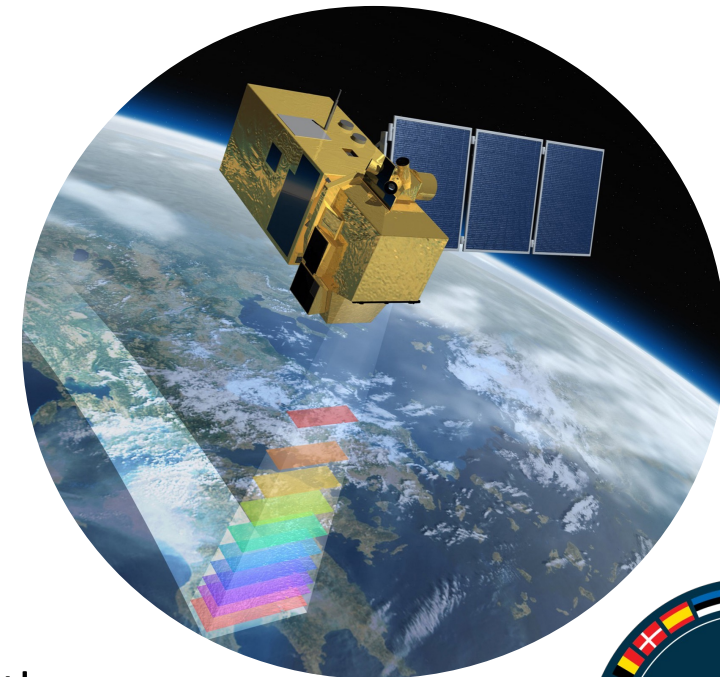
The KVDS Dilemma



4501 Maturity Areas (MA) provided by Zespri corresponding to **1538 KPINs (Zespri's partner farms for G3 project)**



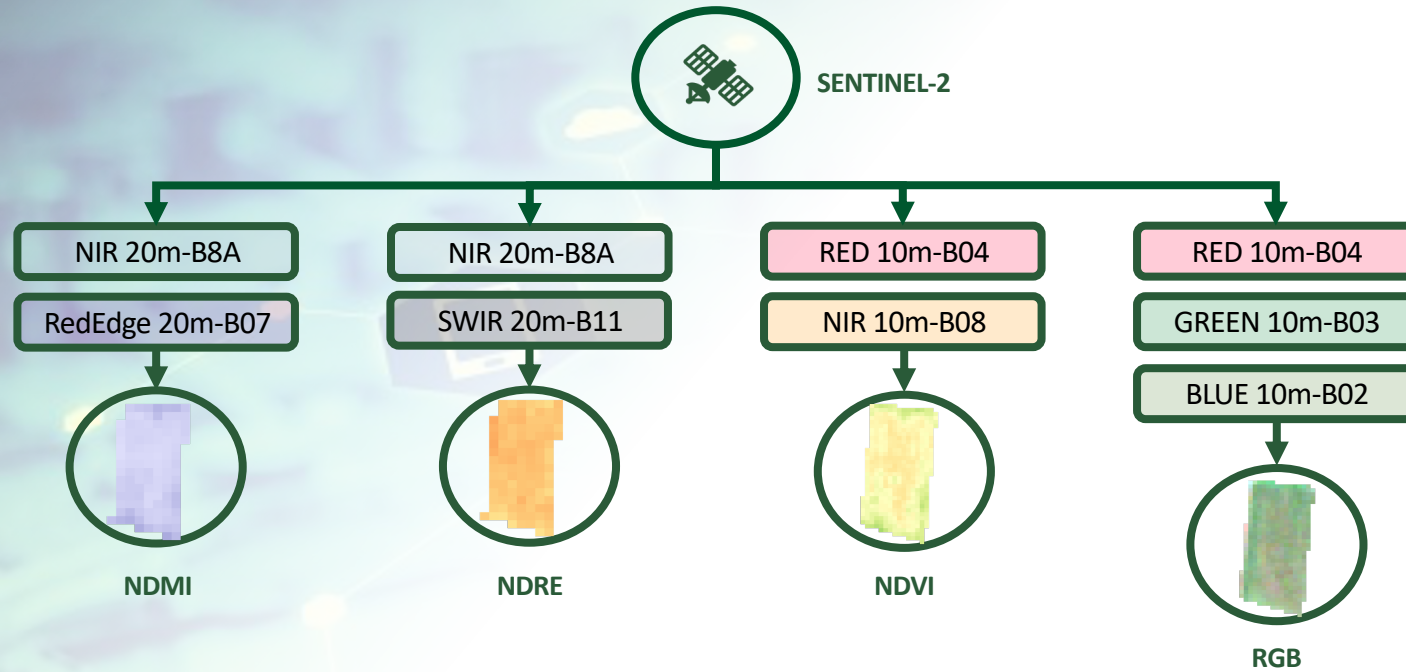
SENTINEL-2



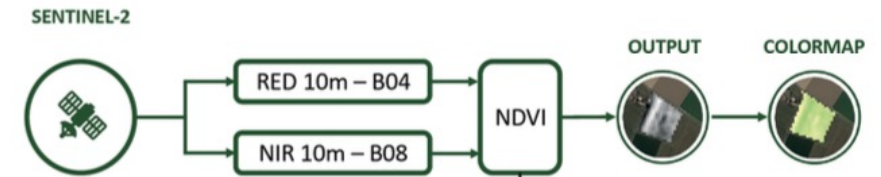
Constellation of **two polar-orbiting satellites** placed in the same sun-synchronous orbit, phased at 180° to each other



The KVDS Dilemma



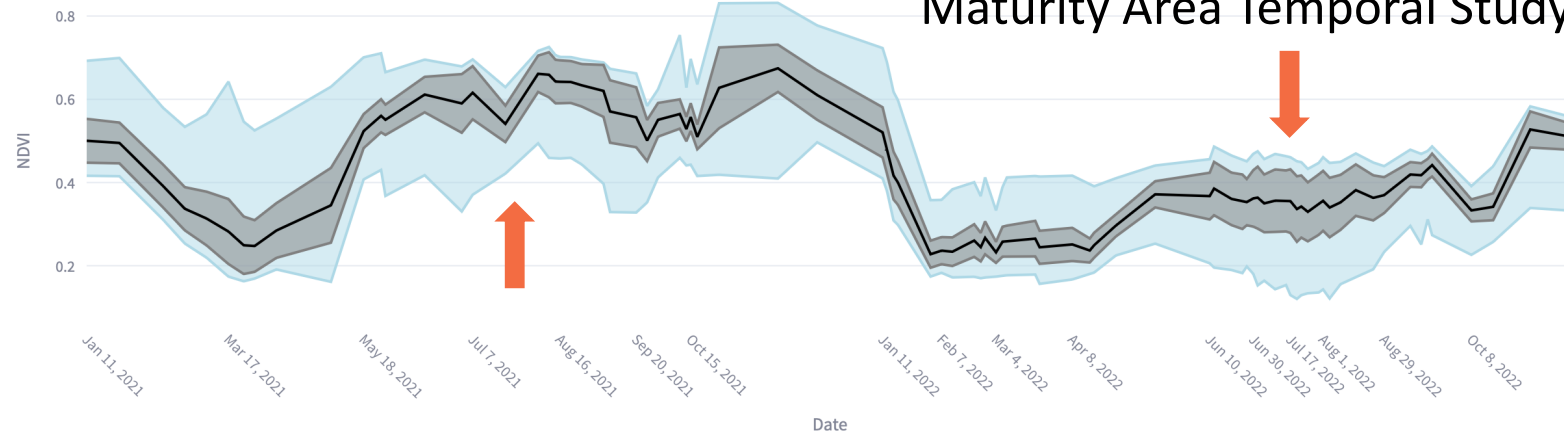
Merging of image data



$$NDVI = \frac{NIR - RED}{NIR + RED} = \frac{B08 - B04}{B08 + B04}$$

Index	Equation Using Landsat 8 OLI [35]
Normalized Difference Vegetation Index (NDVI)	$\frac{NIR - Red}{NIR + Red}$
Enhanced Vegetation Index (EVI)	$2.5 \times \frac{NIR - Red}{NIR + 6 \times Red - 7.5 \times Blue + 1}$
Normalized Difference Water Index (NDWI)	$\frac{(SWIR_1 + Red) + (NIR + Blue)}{(SWIR_1 + Red) - (NIR + Blue)}$
Normalized Difference Moisture Index (NDMI)	$\frac{NIR - SWIR_1}{NIR + SWIR_1}$
Bare Soil Index (BSI)	$\frac{Green + NIR}{Green - NIR}$

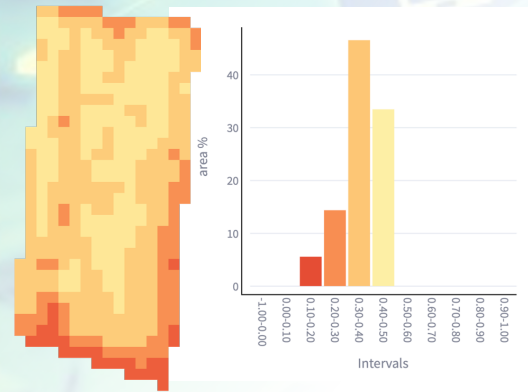
Maturity Area Temporal Study



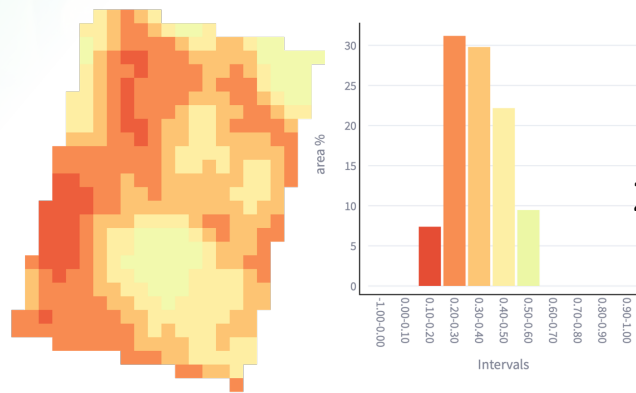
- Higher stress conditions during Q2/Q3 2022 with respect to Q2/Q3 2021;
 - Q2/Q3 2021 -> mean NDVI ~0.6;
 - Q2/Q3 2022 -> mean NDVI ~0.4;
- General condition of stress regardless the presence of KVDS;

The KVDS Dilemma

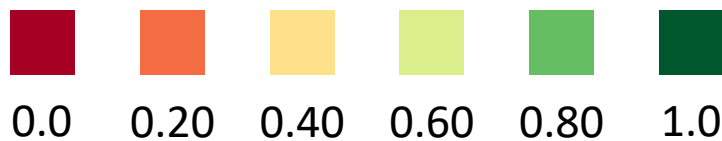
From connectivity analysis we see that both the maturity area has an interval of localized stress. But is it KVDS or not?



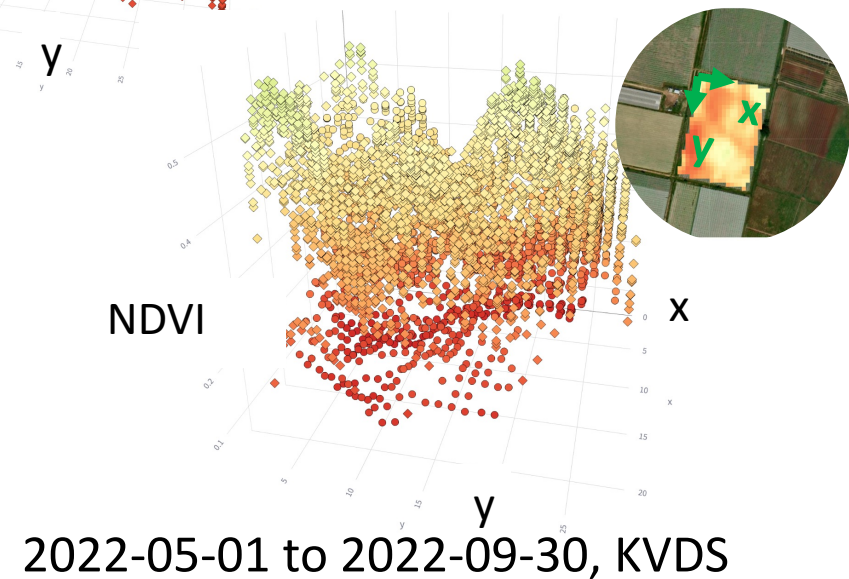
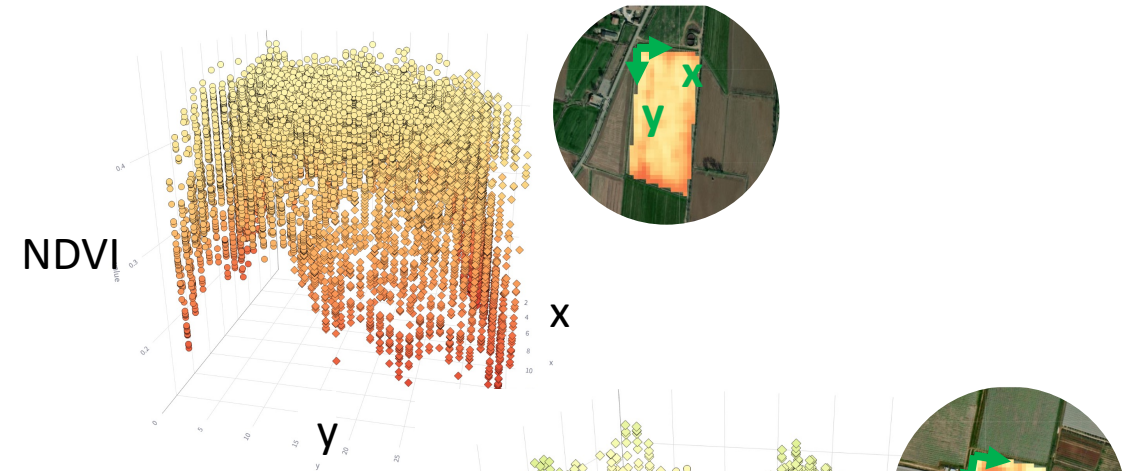
2022-07-15, NO KVDS



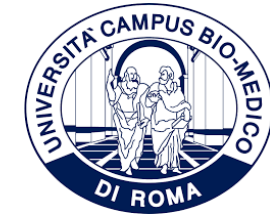
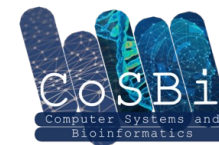
2022-07-14, KVDS



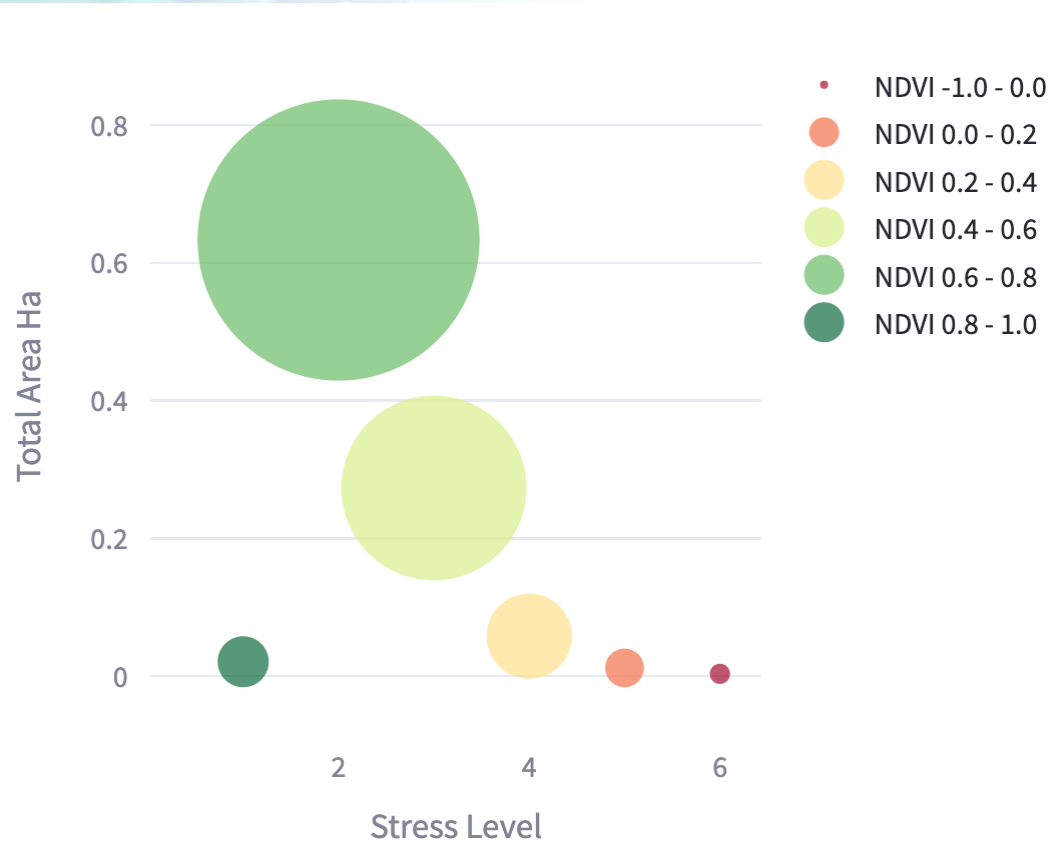
2022-05-01 to 2022-09-30, NO KVDS



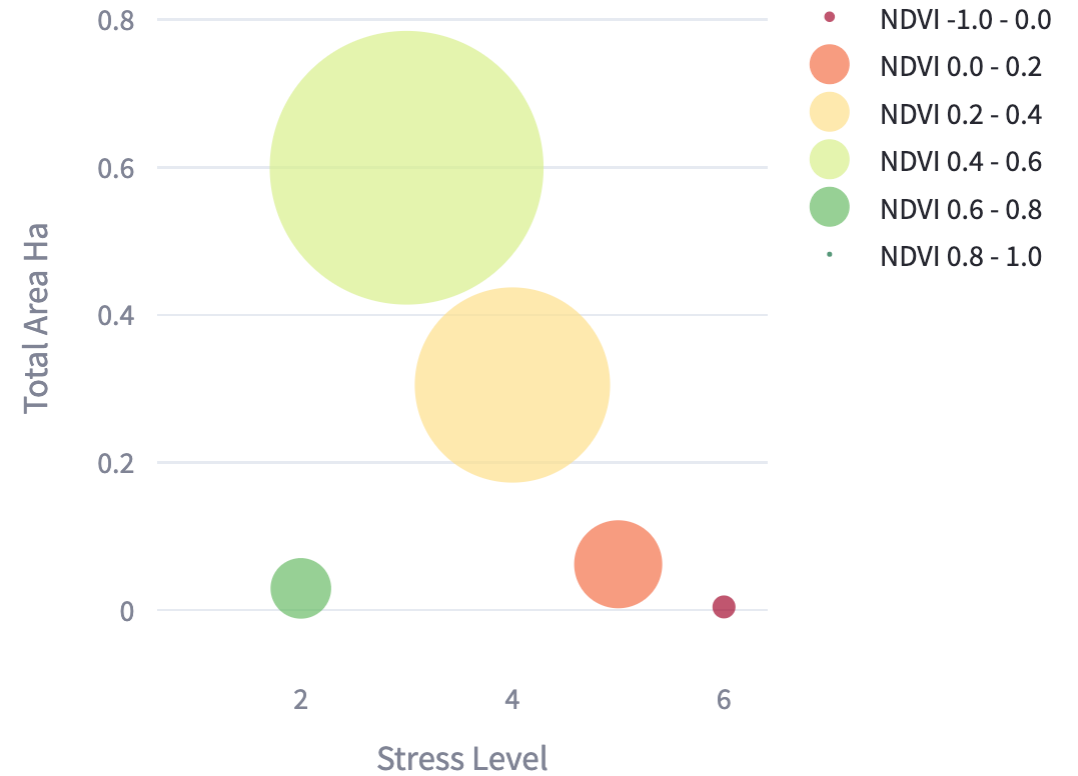
The KVDS Dilemma



Region: Lazio



2021-05-01 to 2021-09-30



2022-05-01 to 2022-09-30